

SERIES 60AD

Optical Encoder with integrated Joystick and Pushbutton

FEATURES

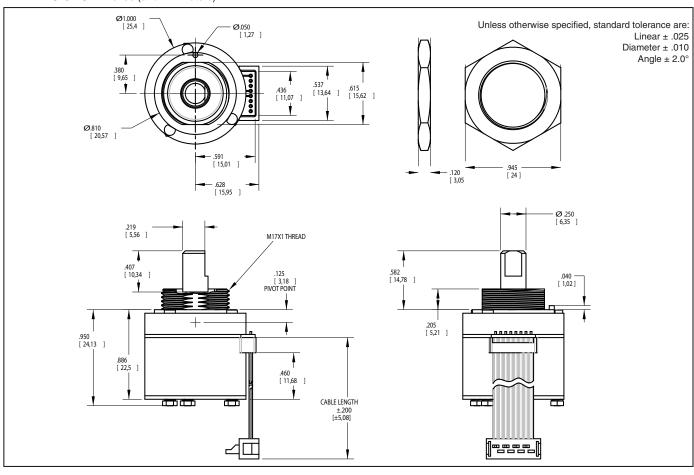
- Dome contacts provide excellent tactile feedback in all directions
- Choices of actuation force, cable length and termination
- Customized solutions available

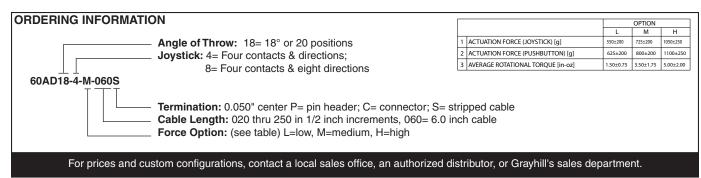
APPLICATIONS

- Aerospace
- Automotive
- Medical devices

DIMENSIONS in inches (and millimeters)

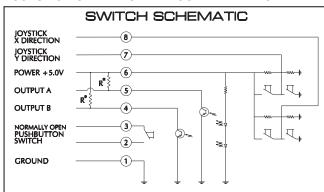






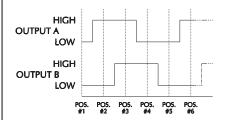


JOYSTICK OPERATION + ENCODER WAVEFORM AND TRUTH TABLE Standard Quadrature 2-Bit Code



*EXTERNAL PULL-UP RESISTORS REQUIRED FOR OPERATION (2.2k Ω).

ENCODER WAVEFORM [C.W. ROTATION]

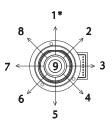


ENCODER TRUTH TABLE [C.W. ROTATION]

POSITION	OUTPUT A	OUTPUT B
#1	0	0
#2		0
#3		0
#4	0	0

○ INDICATES LOGIC-HIGH
 ○ INDICATES LOGIC-LOW
 CODE REPEATS EVERY FOUR POSITIONS

JOYSTICK POSITION DIAGRAM * INDICATES DIRECTION OF D-FLAT ON BUSHING



JOYSTICK TRUTH TABLE

POSITION	X OUTPUT	Y OUTPUT	
1	NEUTRAL	HIGH	
2	HIGH	HIGH	
3	HIGH	NEUTRAL	
4	HIGH	LOW	
5	NEUTRAL	LOW	
6	LOW	LOW	
7	LOW	NEUTRAL	
8	LOW	HIGH	
9	NEUTRAL	NEUTRAL	
•			

SPECIFICATIONS

Rotary Specifications

Operating Voltage: $5.00 \pm 0.25 \, \text{Vdc}$ Supply Current: $20 \text{mA} \, \text{max} \, \text{at} \, 5 \, \text{Vdc}$ Minimum Sink Current: $2.0 \text{mA} \, \text{at} \, 5 \, \text{Vdc}$ Power Consumption: $0.1 \text{mW} \, \text{max} \, \text{at} \, 5 \, \text{Vdc}$ Output: Open collector phototransistor, $2.2 \text{k} \, \Omega$ external pull-up resistors are required Output Code: $2\text{-Bit} \, \text{quadrature}$, channel A leads channel B by 90° in clockwise rotation

Logic Output Characteristics: High: No less than 3.5 Vdc Low: No greater than 1.0 Vdc Mechanical Life: 1 million rotational cycles (through all positions and a full return)

Rotational Torque: see table
Maximum Rotational Speed: 100 RPM
Mounting Torque: 15 in-lbs. maximum
Shaft Push/Pull Out Force: 45 lbs min.
Shaft Side-Load Force: 20 lbs. min.
Terminal Strength: 15 lbs pull-out force min.

Pushbutton Specifications

Rating: 10 mA at 5 Vdc resistive Contact Resistance: less than 10 ohms Contact Bounce: < 4ms make, <10 ms break Mechanical Life: 1 million actuations min.

Actuation Force: see table Pushbutton Travel: .027 ± .010 in.

Joystick Specifications Supply Current: 5mA max Output Code: 2-Bit

Logic Output Characteristics:
Neutral Position: 2.5 ± 0.5 Vdc
High-State Position: >4.5 Vdc
Low-State Position: <0.5 Vdc
Mechanical Life: 500k cycles min.
Actuation Force: see table
Angle of Throw: 3.5° +2°/-1°

Environmental Ratings

Operating Temp. Range: -40°C to 85°C Storage Temp. Range: -55°C to 100°C Relative Humidity: 96 hours at 90-95%

humidity at 40°C

Vibration: Harmonic motion with amplitude of 15g, within 10 to 2000 Hz for 12 hours

Mechanical Shock:

Test 1: 100g for 6ms half-sine wave with a

velocity change of 12.3 ft/s

Test 2: 100g for 6ms sawtooth wave with a

velocity change of 9.7 ft/s

Materials and Finishes Detent Housing: Nylon 6/10

Shaft: Nylon 6/10

Shaft Insert: 303 stainless steel Joystick Housing: Nylon 6,10 Centering Plate: Nylon 6,10 Detent Balls: Carbon steel Detent Springs: Music wire Dome Contacts: Stainless steel

Dome Housings: Polycarbonate over brass-

lead frame

Dome Retainers: Nylon 6,0; 30% glass-filled **Joystick Actuators:** Polyphthalamide; 50%

glass filled

Pushbutton Dome Retainer: Polycarbonate Printed Circuit Board: NEMA grade FR-4. Glass-cloth epoxy, double clad with copper Infrared Emitter: Gallium arsenide

Phototransistor: Planar silicon

Resistors: Metal oxide on ceramic substrate **Solder:** 95.5% SN, 3% AG, 0.5% CU

OPTIONS

Contact Grayhill for custom terminations, rotational torque, number of positions, shaft configurations, and resolutions.